

# Chapter 27

## Restoration Within Protected Areas: When and How to Intervene to Manage Plant Invasions?

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**Abstract** Despite the on-going efforts to set aside land for conservation, biodiversity is increasingly being threatened by factors such as invasive alien species that do not recognise these boundaries. Invasive species management programmes are widely incorporated into protected area management plans; however, the success of these programmes hinges on the ability to identify when a system will be able to recover after invader control and eradication efforts and when further intervention will be necessary to aide recovery. Invasive alien plants can alter ecosystem attributes to produce strong legacy effects that prevent the recovery of a system. Here we provide a framework for how to identify and incorporate recovery constraints into restoration efforts. Identifying recovery constraints can help improve how ecological theory – assembly rules, ecological succession, and threshold dynamics – can be used to guide restoration efforts.

**Keywords** Assembly rules • Ecological succession • Threshold dynamics • Recovery constraints • Invader impacts

### 27.1 Introduction

Protected areas (PAs) serve as the primary method to maintain and protect global biodiversity (UNEP-SCBD 2001). Therefore, an important goal in PAs is to minimise threats to biodiversity and maintain ecological communities in their natural states (Lockwood et al. 2006). Protected areas can manage certain threats such as deforestation or poaching, but even the most well managed reserves are still

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susceptible to threats such as climate change, pollution, and invasive alien species that do not recognise these conservation boundaries and fence lines. We focus on managing one of these threats, invasive alien plant species (IAPs), in PAs. In response to this threat, many PAs have implemented large-scale invasive species management programmes that employ prevention, eradication, and control strategies aimed at slowing or stopping the process of invasion (Foxcroft and Richardson 2003; Doren et al. 2009b).

Increasingly, a challenge in this process is that simply removing the invasive species is not sufficient to restore native biodiversity. A recent review by Kettenring and Adams (2011) found that invasive removal successfully reduced the cover of invasive alien plants (IAP), but did not always result in native species recovery. Further intervention – with a focus on restoration – may be necessary to take into account the impacts an invader has on a system (D’Antonio and Meyerson 2002), as well as address recovery constraints of the native community. However, these additional intervention actions can be costly in terms of time and money and, in some cases, they have unintended consequences and actually slow recovery (Zavaleta et al. 2001; Hobbs and Richardson 2011). Integrating additional intervention efforts within an existing protected area management plan can be complicated by a variety of factors such as limited resources (e.g. staff and infrastructure), legal mandates under IUCN management categories, or differing agendas among the stakeholders in the governance group (Keenleyside et al. 2012). The isolated nature of PAs requires intervention efforts to be a concerted endeavour with agencies/land owners outside of the reserve, further complicating the success of management efforts.

In this chapter, we focus on this conundrum: when should we expect a system to recover without additional restoration efforts after invasive species control efforts? And when is further intervention necessary for recovery? Resources are often scarce for PAs, with eradication and control of invasive species often consuming a disproportionate amount of reserve budgets (D’Antonio and Meyerson 2002). Identifying necessary points of intervention prior to action is therefore critical for successful protected area management. We begin by providing an overview of invader impacts that may constrain and preclude the recovery of a system after IAP management. We then explore key ecological theories that can be used to guide restoration strategies. Finally, we discuss how land managers could adjust restoration efforts depending on the constraints present in the system.

In this chapter, we consider restoration to include both IAP control and eradication efforts as well as additional actions to aid native recovery. As emphasised elsewhere in this volume, invader management plans in PAs often include control and eradication efforts in tandem with native recovery efforts. Here, we focus on restoration after the invaders are removed or reduced. The key questions are thus: when will passive recovery following these efforts be sufficient to recover desired native communities, and when will active intervention (*sensu* Suding 2011) be needed?

## 27.2 Invader Impacts and Recovery Constraints

As PAs operate under the mandate to protect local biodiversity, the continuing and growing threat of IAP invaders on native biodiversity has made IAP management a priority for PAs (Macdonald et al. 1988; Vitousek et al. 1997; McNeely 2001). Understanding invader impacts on ecological communities is an important first step in understanding how native communities may recover following IAP control. We particularly focus on IAP legacy effects in PAs, where the impacts of invasion persist even after invader control or eradication. In these cases, removing the invader may not always lead to successful recovery of the degraded system (D'Antonio and Meyerson 2002); additional management and restoration actions may be necessary to put the native community on a path to recovery (Suding et al. 2004). Alternatively, if an IAP does not have strong legacy effects, additional efforts may not be necessary and native communities should be expected to passively recover following control efforts. Importantly, the impacts of invasion may occur either progressively with invader abundance or abruptly once the invader reaches a certain abundance threshold (D'Antonio and Chambers 2006; Didham et al. 2007). Consequently, whether active or passive restoration is necessary may depend on the pattern as well as the nature of legacy effects.

Native species recovery may often be limited by dispersal following IAP control (Galatowitsch and Richardson 2005; Traveset and Richardson 2006). Source populations of native species may be far from the restoration area (McKinney and Lockwood 1999) or seed dispersal networks may be altered in the invaded area (Traveset and Richardson 2006; McConkey et al. 2012). For example, in Australia, recovery of coastal dune communities invaded by *Chrysanthemoides monilifera* subsp. *rotundata* (the South African bitou bush) is limited by poor seed dispersal from existing native vegetation (French et al. 2011), and in New Zealand, native shrublands dominated by *Kunzea ericoides* (kanuka) have a different composition and a smaller abundance of the avian seed dispersers compared to *Ulex europaeus* (gorse) invaded stands (Williams and Karl 2002). Additionally, native seed bank at a restoration site could be diminished if natives have been absent or in low abundance, reducing the potential for recovery from in situ germination (D'Antonio and Meyerson 2002). In southern California, passive recovery of the native coastal sage scrub community is limited due to the depauperate native seedbank in long term invaded alien grassland sites (Cione et al. 2002; Cox and Allen 2008).

Plant invaders can alter disturbance regimes, which may create positive feedbacks that promote invader success (D'Antonio and Vitousek 1992; Mack and D'Antonio 1998). These feedbacks must be disrupted to allow the recovery of a system (Suding et al. 2004). A widespread example occurs when annual grass invaders increase the intensity and frequency of fire (D'Antonio and Vitousek 1992). In the Western United States, for example, alien annual grasses increase fuel loads, which promotes a fire frequency for which the resident community is not adapted (Whisenant 1990). Conversely, IAPs can also impact disturbance regimes by suppressing disturbances (Mack and D'Antonio 1998). *Schinus terebinthifolius*

(pepper tree) invasion in Florida's Everglades National Park has suppressed fire intensity by decreasing fuel loads (i.e. understory vegetation), which enhances its own recruitment (Doren and Whiteaker 1990). In these cases, the disturbance regime may not recover following IAP control, and additional actions may be needed to re-establish the disturbance regime needed to support the native community (Davies et al. 2009).

Invasive alien plants can also impact the physical structure of soils by increasing erosion rates or sedimentation rates and directly by affecting substrate stability (D'Antonio et al. 1999), resulting in soil legacies (*sensu*, Corbin and D'Antonio 2004). For example, while increased sedimentation can promote succession and facilitate the establishment of native species in degraded forests in Algiers (Wojterski 1990), increased erosion rates can limit recovery by eliminating habitat for native species and promoting the establishment of introduced species in the South African fynbos (Macdonald and Richardson 1986).

Soil legacies can also influence belowground biological processes that promote IAP abundance and stall native species recovery (van der Putten et al. 2007; Inderjit and van der Putten 2010). An invader can be successful because it is able to escape soil pathogens (Klironomos 2002), and it may also alter pathogen incidence in the native community to reduce competitive effects and facilitate its spread (Eppinga et al. 2006; Mangla et al. 2008). Pathogen loads may slow the recovery rates of communities, as they continue to influence the performance of native species even after IAP removal (Malmstrom et al. 2005). Invasive alien plants can facilitate their invasion by allelopathy (i.e. the release of phytotoxins, which inhibit the growth of neighboring plants; Callaway and Ridenour 2004). For example, high impact invader *Centaurea maculosa* (spotted knapweed) releases a compound that inhibits root growth of its neighbouring plants (Bais et al. 2003). Additionally, *Alliaria petiolata* (garlic mustard), a widespread invader in North American forests, secretes compounds that inhibit the symbiotic mycorrhizal associations of native plants. These altered relationships can prevent the recovery of the community once the invader has been removed due to residual toxins (Perry et al. 2005). Other invaders can alter soil properties such as salt concentrations or soil pH, reducing the potential for subsequent colonization by native species (Vivrette and Muller 1977; Conser and Connor 2009).

Soil legacies also include invader impacts on biogeochemical cycles that alter resource availability (Mack et al. 2001; Ehrenfeld 2003). Nitrogen cycling rates are regularly increased by invaders by altering the microbial community (Hawkes et al. 2005), altering litter quality (Sperry et al. 2006), or directly by nitrogen-fixing species (Vitousek and Walker 1989; Le Maitre et al. 2011). Increased nitrogen availability can result in positive feedbacks that maintain the invaded state, thwarting recovery efforts (Clark et al. 2005). For example, in temperate grasslands in Australia, alien annual species that invade native perennial tussock grasslands can alter nitrogen cycling to favour their own growth. These nutrient changes are sufficient to push the system past a threshold, preventing the recovery of native grasses (Prober et al. 2009). Lastly, invaders can also alter the hydrology of a system via altered transpiration rates, rooting depths, phenology, and growth

rates (Levine et al. 2003). *Tamarix* spp. (salt cedar) invasion in the south-western United States has resulted in higher transpiration rates and marginal water loss due to the salt cedar's deeper root system in this water limited system (Zavaleta 2000).

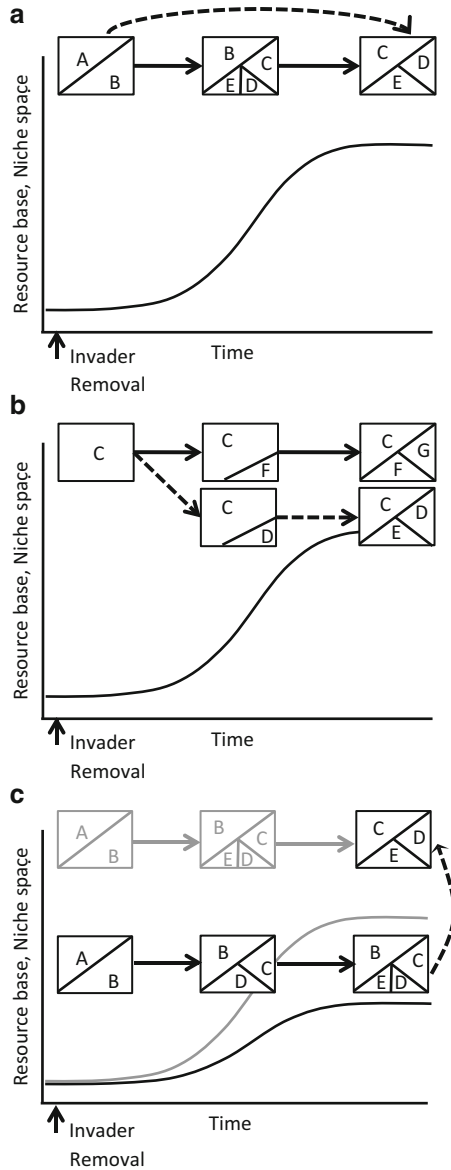
## 27.3 Ecosystem Models in Restoration

While it is clear that many IAPs have strong legacy effects that can influence the recovery of native communities, it is also important to put these effects in the context of ecological processes that guide the path to recovery (Young et al. 2005; Hobbs et al. 2007; Suding and Hobbs 2009). Conceptual models of ecosystem dynamics such as assembly theory, ecological succession, and threshold dynamics can guide restoration projects by providing insights into these ecological processes (Fig. 27.1). In the following paragraphs we explore these three concepts and how they can guide decisions about when and how to intervene in PAs following invasive plant control efforts. For each, we first present the basic framework, then a case study examining application to restoration in PAs.

### 27.3.1 Assembly Rules

Assembly theory focuses on how a suite of processes (e.g. dispersal, disturbance, environment, competition) influence which species are able to establish over time (Young et al. 2001; Temperton et al. 2004; White and Jentsch 2004; Hobbs et al. 2007). This framework integrates these processes into a series of filters (dispersal, environmental, and biotic) that act at varying spatial scales, which can explain which species from a regional species pool (large scale) are found in the local community (small scale, Weiher and Keddy 1995; Diaz et al. 1998, 1999). In the context of native species recovery following IAP control, recovery requires that filters at each scale allow native species to establish and persist (Fig. 27.1b). Additional intervention efforts would be focused on the filters that excluded the desired species from recovering (Fig. 27.1b, dashed arrow).

Three general types of filters are emphasised in assembly theory. The first filter that species must overcome is dispersal: species must have dispersal traits that allow them to arrive at a site (Levine and Murrell 2003). As discussed above, invasive plants can increase the dispersal limitation of native species in many ways, creating new barriers to the dispersal filter for some native species. If a species is able to colonise a site, the next filter acting upon it is the environmental filter. To successfully cross the environmental filter, a species must have the suite of traits that allow it to survive the given environmental conditions (Weiher and Keddy 1995; Diaz et al. 1998, 1999). Soil legacies of invasive plants, such as erosion and resource cycling impacts, can alter this filter. An extension to the environmental filter is the disturbance filter (White and Jentsch 2004), which invasive species may



**Fig. 27.1** Recovery trajectories after invader removal, (a) assuming little invader impact or, (b) and (c), a legacy of invader impacts. Species composition is symbolised by the *capital letters* and abundance by proportion of each square; the desired goal community is C/E/D. *Solid lines* indicate scenarios with passive restoration after IAP removal; *dotted arrows* indicate restoration intervention. We present scenarios consistent with each of the three ecosystem models of recovery. Successional theory (a) is most appropriate in systems where there is little expectation of strong invader impacts. In (a), successional theory assumes directional change in species composition over time. If the natural recovery takes too long, land managers can intervene to accelerate recovery (*dashed arrow* in a). In systems impacted by invader legacy affects (b, c), assembly theory and threshold theory may be most appropriate to guide restoration efforts. In (b), IAP legacies affect the order of species arrival. Active intervention can focus on adding species,

similarly alter. The final filter in assembly theory is the biotic filter, which restricts the community to those species that can coexist in the presence of interspecific interactions (MacArthur and Levins 1967; Tilman 1990; Chesson 2000). Under the biotic filter, competitive interactions would limit the co-occurrence of functionally equivalent species due to niche limitation resulting in limited similarity among species within community (MacArthur and Levins 1967). Under situations where invasive species have been controlled or eradicated in PAs, we would expect that this biotic filter would be less of a consideration compared to the other filters, but it would be important to manage were reinvasion possible.

The efficacy of active intervention efforts in restoration (e.g. species palette for planting, selection of planned disturbance to limit competitive interactions) can be assessed in this assembly filter framework by equating restoration actions with changes in assembly filters (Funk et al. 2008). For example, seed addition or planting of native species can be viewed as changing the dispersal filter at a site. Similarly, a trait-based approach could increase the success of restoration efforts areas where managers fear invasive species could re-invade following control efforts by identifying a suite of native species with traits similar to the IAP to enhance the invasion resistance of the community, thereby strengthening the biotic filter (Funk et al. 2008).

### 27.3.2 Case Study 1: California Grasslands

Protected areas such as county parks and reserves within California are often imbedded within a highly fragmented landscape (Greer 2005). In California PAs, alien annual grasses have the potential to gain access to the interior of natural areas by initially colonizing disturbed roadside areas (Gelbard and Belnap 2003). Roadsides can have large inputs of atmospheric nitrogen deposition (Pearson et al. 2000), which can interact with local grassland's N cycling to increase N availability (Sirulnik et al. 2007), and further promote these annual grasses (Padgett and Allen 1999). Furthermore, prolonged dominance of alien grasses within a site can reduce the seedbank of native species and prevent the recovery of a system once the grasses have been removed (Cione et al. 2002).

To evaluate if the biotic filter can be manipulated to slow or stop the re-invasion of aliens after control, Cleland et al. (2013) conducted a restoration experiment along a roadside edge of the Laguna Coast Wilderness Park in southern California



**Fig. 27.1** (continued) affecting the order of species arrival, to guide the assembly process to arrive at the target community. In (c), recovery may result in a new undesired state due to invader legacy impacts, preventing the successional process that would occur naturally (*grey boxes*). A threshold model may be the most appropriate to apply in cases such as these, where multiple restoration activities would need to be done to overcome this feedback (*dashed arrow*, c) (Modified from White and Jentsch 2004)

where they manipulated nitrogen availability and added native seeds representing different functional groups (annual/perennial grasses, early/late forbs and N-fixing legumes). In the first year, they removed alien annual grasses and forbs. Then in the second year, they allowed alien species to colonise naturally. Native communities with low N availability and in which early forb seed was added best resisted re-invasion. Thus, they found that by altering resource availability and adding species that have similar phenology to the problematic invader they could manipulate the biotic filter to increase invasion resistance.

### 27.3.3 *Ecological Succession*

Successional dynamics, the changes in species composition within a community over time, have been a classic and focal question in ecology since the 1900s (Cowles 1899; Clements 1916; Gleason 1926). Succession traditionally describes the patterns of compositional change after a disturbance (Clements 1916; Pickett et al. 1989) but recent studies have gone beyond describing the patterns to identify the mechanisms, which influence these patterns (Connell and Slatyer 1977; Tilman 1988; Pickett et al. 2009). As successional theory has expanded to incorporate the possibility of multiple successional pathways versus a single climax community (Glenn-Lewin et al. 1992), comparing and analysing successional trajectories has been adopted to describe the temporal change in community composition (Hobbs and Mooney 1995). Once a disturbance occurs at a site, the availability of safe sites and propagules for colonization in conjunction with the impacts of established species determine subsequent successional dynamics (Pickett et al. 1987). In the context of whether to intervene following invasive species control, additional intervention activities can be viewed as either altering or initiating any of these recovery processes (del Moral et al. 2007; Fig. 27.1a).

Ecological restoration can take a variety of approaches to manage succession toward a desired target. The first and simplest approach is to allow succession to occur unaided (spontaneous succession, Prach et al. 2001) and should be a viable option if most abiotic and biotic functioning remain intact after invasive species control (Lockwood and Samuels 2004; Prach and Hobbs 2008). However, in the case of large-scale invasions, natural succession is unlikely to be a viable option as legacies from the invader may influence recovery (Zavaleta et al. 2001). When legacies are present another approach is to assist succession via manipulations to the physical environment and to biotic processes that may be important within the target system (technical reclamation, Prach et al. 2007). Technical reclamation may be necessary if invasion has resulted in the complete loss of any of the overarching processes governing succession (e.g. availability of safe sites, propagules, and species impacts; del Moral et al. 2007; Prach and Hobbs 2008). The third approach, assisted succession, is a combination of technical reclamation and spontaneous succession in which site conditions are initially modified to support native species but subsequent succession is allowed to occur naturally (Prach et al. 2007;



Fig. 27.1a, dashed line). This approach has been implemented within rangeland invasive plant management, by pairing removal efforts with post-removal restoration activities (Sheley et al. 2010). While this framework is similar to assembly theory in that it emphasises identification of processes that constrain recovery, it also emphasises trajectories of community development over time.

### 27.3.4 Case Study 2: South African Fynbos

The fynbos vegetation in the Cape Floristic Region of South Africa is highly impacted by alien trees and shrubs (*Acacia* spp; Macdonald 1984; Le Maitre et al. 2011). *Acacia* spp. are nitrogen (N)-fixing plants, which can increase soil fertility after an extended presence in an area (Yelenik et al. 2004). They also have a large impact on water resources, as they consume more water than the native vegetation (Le Maitre et al. 2000). Under the national ‘Working for Water’ program, *Acacia* spp. and other woody invasive plants have been targeted for removal (Turpie et al. 2008). Clearing of these invaders is often a combined effort of cutting down the tree/shrub and, for those species that resprout, applying herbicide to the stumps with the felled biomass left on site. It can also involve the removal of the felled material and/or burning (Macdonald 2004). Cleared sites are often allowed to recover spontaneously after treatment; however, the success of passive recovery is often dependent on the type of treatment (i.e. spontaneous succession was the most successful with clearing and removal and the least successful under burning; Blanchard and Holmes 2008). Blanchard and Holmes (2008) found that once the biomass was removed, native species had space to establish and assisted succession approaches were needed. For example, seeding after burn treatments to overcome dispersal constraints can increase the presence of native fynbos vegetation and enhance natural recovery; however, continuous eradication efforts are needed until the large *Acacia* seedbank is reduced as natural wildfires may continue to promote the establishment of *Acacia* after initial removal (Milton and Hall 1981).

### 27.3.5 Threshold Dynamics

Ecological thresholds are a breakpoint between two systems that, when crossed, result in an abrupt change in community states (Holling 1973). Thresholds occur due to positive feedback mechanisms, which make systems resistant to change (Folke et al. 2004; Suding et al. 2004). While successional models and recovery pathways apply to many situations of recovery following IAP control, threshold models can help explain why some systems are not able to recover once the invader has been removed (Prober et al. 2009). In the context of these ‘stuck’ systems, threshold models point to the importance of breaking these positive feedbacks in order to facilitate recovery (Fig. 27.1c).

A useful framework for incorporating ecological thresholds into management has been to divide thresholds into two stages. The first stage is the biotic threshold, which can be identified by changes in vegetative structure or composition (Friedel 1991; Whisenant 1999). The second stage is an abiotic threshold, which identifies changes in ecosystem functioning (Whisenant 1999). Because impacts on functioning are thought to lag behind biotic changes, a system is thought to first encounter the biotic threshold and subsequently the abiotic (Whisenant 1999; Hobbs and Harris 2001; Briske et al. 2005). Invasive alien plants that trigger biotic threshold changes may be easier to control than those that cause biotic and abiotic threshold changes. Invaders that cause the system to cross both thresholds (ecosystem engineers, *sensu* Jones et al. 1994) make the success of restoration efforts highly uncertain (Ehrenfeld et al. 2005; Kulmatiski 2006; Doren et al. 2009a). Once management has identified key variables that can indicate whether a threshold has been crossed, this knowledge can be incorporated into management to identify when and what management efforts are needed to increase the success of control and subsequent restoration efforts (Foxcroft and Richardson 2003; Doren et al. 2009b).

### 27.3.6 Case Study 3: Australian Subtropical Rainforests

One of the world's most notorious invaders, *Lantana camara* (lantana), has invaded and replaced much of the native vegetation in the subtropical forests in eastern Australia (Lowe et al. 2000; Bhagwat et al. 2012). *Lantana camara* was introduced as an ornamental shrub in the mid-nineteenth century (Swarbick 1986) but has rapidly spread to the detriment of native diversity, including PAs within Australia's national parks. Many of the national parks within eastern Australia are isolated within a highly disturbed system, a problem common to many PAs globally (Fox et al. 1997). Edges between the reserves and disturbed areas (e.g. old agricultural fields in Australia) make reserves vulnerable to weedy invaders such as *L. camara*, which readily spread across disturbed landscapes (Gentle and Duggin 1997; Stock 2004).

However, this landscape also provides an opportunity to investigate the dynamics that allow this invader to invade pristine habitats. Stock (2004) and Gooden et al. (2009) monitored *L. camara* and native plant abundance in national parks in eastern Australia and were able to identify two separate thresholds. After measuring *L. camara* cover and canopy cover in gaps in two national parks, Stock (2004) identified a first invasion threshold: forests whose canopy cover is 75 % native species can prevent the establishment of *L. camara*, because the woody invader is shade intolerant in those forests. If *L. camara* reaches 75 % cover, however, the system crosses a second biotic threshold identified by Gooden et al. (2009) in which native species richness falls dramatically, likely due to *L. camara* effects on soil fertility (Bhatt et al. 1994) and soil seed banks (Fensham et al. 1994). These

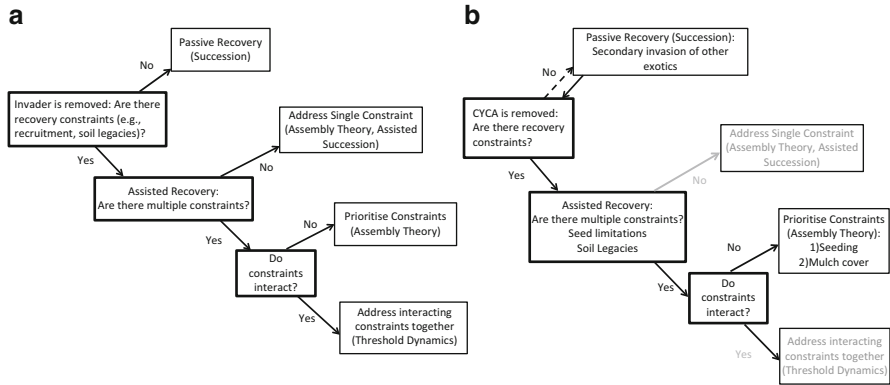
thresholds, which identify when a community can resist invasion and when invader impacts begin to increase dramatically, are being used to guide an integrated management plan (Stock 2005).

## 27.4 Addressing Recovery Constraints in the Context of the Three Models

The ability of ecosystems to recover after IAP control greatly varies and is often contingent on the system's intrinsic rate of recovery, its level of degradation, and its surrounding matrix (Jones and Schmitz 2009; Holl and Aide 2011; Gaertner et al. 2012). This variability makes it difficult to assess when land managers should intervene and implement additional restoration practices or leave a system to recover naturally (passive restoration, *sensu* Suding 2011). For example, in the south-western United States, invader removal without any paired plantings of native flora can detrimentally affect local fauna (Zavaleta et al. 2001), and yet, active plantings in the tropics may prevent the establishment of native flora and slow natural recovery (Murcia 1997). Furthermore, within PAs, additional complicating factors such as land use and pollution are either well documented or less severe than in non-protected areas. Therefore, restoration efforts conducted within PAs after IAP removal can help improve our collective understanding of invader impacts and recovery constraints. In this section, we suggest a series of steps to decide when additional intervention following IAP control may be needed.

First, an understanding of the extent of IAP impacts and whether they will persist following invader removal is critical (Sheley et al. 2010). A holistic assessment should try to identify the causes of the invasion as well as impacts of the invasion (see invader impacts section above; James et al. 2010). If a holistic assessment was not initially available, small scale experiments can be used to identify restraints (Kettenring and Adams 2011). Simply observing the natural recovery of a system after control efforts would also aide the decision of whether or not to intervene when assessments are not available (Holl and Aide 2011). If monitoring indicates natural recovery, land managers can use successional theory to make inferences about the trajectory of the system (Sheley et al. 2006; Prach and Walker 2011). However, if monitoring identifies invader legacies, the success of management efforts is contingent on effectively prioritizing and addressing those recovery constraints (Fig. 27.2a; Suding et al. 2004).

Identification of constraints can be done through knowledge of natural history, experimentation (Gaertner et al. 2011; Kettenring and Adams 2011) or research from other sites (e.g. recent reviews of the effects of the invaders *Acacia* (Le Maitre et al. 2011) and *L. camara* (Bhagwat et al. 2012) on ecosystems). If one single factor seems to strongly constrain recovery, natural recovery should be fairly straightforward if land managers can address the single constraint



**Fig. 27.2** (a) Decision Tree Model for assessing restoration activities following invader control efforts. Decision making nodes represent the assessment of identity, number of and interactions between recovery constraints (**bolded boxes**). At low and medium IAP abundances, control/removal efforts may be sufficient to return a community to its restored state (node 1: No intervention). However, at medium and high invader abundances management actions may not be sufficient to achieve the full recovery of the degraded system due to recovery constraints. A recovery constraint assessment can guide decisions for subsequent restoration actions (nodes 2 & 3). Ecological principles (*listed in parentheses*) can help inform which restoration tools to use. (b) Decision Tree model for the control and restoration efforts for *Cynara cardunculus*. Initially management efforts relied on passive recovery (*dashed line*); however after observing the ineffective recovery of native species, the land managers decided to implement efforts to overcome constraints. Evaluation of constraints (supporting citations listed in case study) indicated two potential constraints, and after determining that they likely do not interact to synergistically thwart recovery, constraints were prioritised. *Grey boxes* indicate paths that were not followed in this scenario

(Prach et al. 2001; Lockwood and Samuels 2004). Successional theory and assembly theory would be helpful in guiding restoration efforts with single constraints (Suding and Hobbs 2009). However, if multiple constraints are present, it is important to assess whether these constraints can be addressed independently or need to be addressed in tandem (Suding et al. 2004). If multiple constraints synergistically thwart the recovery of a system, it would be essential to address the constraints in tandem to disrupt any feedbacks that are preventing recovery (Fig. 27.2a; Suding et al. 2004).

Constraints can operate at multiple spatial and temporal scales (Suding and Hobbs 2009), and processes operating at one spatial or temporal scale can interact with processes operating at another scale to create strong internal feedbacks that prevent the recovery of the system (cross-scale interactions; Peters et al. 2007). In a hypothetical example, if an invader disrupted dispersal processes and produced soil legacies via allelopathy, successful restoration efforts would have to address both the soil condition as well as the dispersal constraint. Threshold models address strong internal feedbacks and nonlinear dynamics within ecosystems and would be helpful in guiding restoration efforts with interacting constraints

(Suding and Hobbs 2009). If the constraints do not interact, it would be important to prioritise constraints, and assembly theory could help elucidate which constraints and potential restoration approaches could be addressed based on how the degraded system has deviated from the historical environmental and biotic conditions (Lockwood and Samuels 2004). However, projects that incorporate several restoration actions are often more successful; therefore if resources are available, it would be wise to tackle multiple constraints (augmentative restoration; Bard et al. 2004; Buisson et al. 2008). While these approaches can help a land manager make better a priori decisions about what restoration activities to undertake, this approach is not fool proof and should always incorporate monitoring and re-assessment to ensure that the system is moving in the desired direction.

#### **27.4.1 Case Study 4: Sustainable Control Efforts of *Cynara cardunculus* (Artichoke Thistle) in Orange County, California**

*Cynara cardunculus* was introduced into southern California in the nineteenth century and has become a problematic invader across local grasslands (Thomsen et al. 1986). It is a perennial species with a deep taproot (about 1.5 m) and large inflorescences (up to 50 per rosette; Marushia and Holt 2006) filled with up to 800 wind dispersed seeds (Kelly 2000). It forms dense species-poor stands (Bowler 2008). Within the Nature Reserve of Orange County, it has invaded over 1,618 of the 14,973 ha of protected open space and its control has dominated the Reserve's budget for invasive species management (McAfee 2008). The primary control method since 1994 has been direct herbicide application with the assumption that native communities would passively recover. However, after 13 years native species did not recover in all treated areas; instead, the abundance of other alien plants increased (Seastedt et al. 2008). In an effort to implement more effective management activities for native grassland recovery, potential constraints were further identified using other published research studies. For example, seed limitation is often a constraint for native grass populations across California (Seabloom et al. 2003; Seabloom 2011). Additionally, Potts et al. (2008) identified that litter quantity and quality changes due to *C. cardunculus* invasion, which can negatively impact native recovery (Bartolome and Gemmill 1981; Coleman and Levine 2007). These findings can be integrated into a potential management plan for efficient and sustainable management of treated areas (Fig. 27.2b), where the passive recovery approach would be replaced with one where seed limitation and soil legacies constraints are both prioritised within the reserve.

## 27.5 Conclusions

Ecosystems globally are undergoing rapid changes due to global change drivers such as CO<sub>2</sub> enrichment, atmospheric nitrogen deposition, climate changes, land use, and biotic invasions (Sala et al. 2000). Among these drivers are invasive species, which are an increasing threat to natural and working landscapes as the globalization of trade and interactions with other global change drivers increase the opportunities for introductions (Levine and D'Antonio 2003; McNeely 2006). A small fraction of those invaders have the potential to trigger large changes in ecosystem functioning as they spread across a landscape (Williamson 1996) and can contribute to the degradation of native communities (McNeely 2001). Protected areas have the unprecedented burden of minimizing these negative invader impacts as they are tasked with the goal of protecting and maintaining the globe's biodiversity.

Here, we emphasised ways to determine whether additional intervention is needed for native recovery following IAP control in PAs. Multiple lines of evidence need to be weighed to best gauge when and where to invest in additional intervention approaches and when to stand back and allow the native system to recover naturally. This decision-making is not clear-cut but can be based on several ecological frameworks describing how communities are assembled and recover over time. Protected areas benefit from a holistic management approach, which addresses IAP detection, sources of invaders, potential external stressors, and management thresholds dictating when management efforts need to be initiated (Zavaleta et al. 2001; Foxcroft and Richardson 2003; Clewell and McDonald 2009). Worldwide efforts to evaluate the effectiveness of management within PAs (Hocking et al. 2000) provide a unique opportunity to assess the link between ecological theories that frame the process of recovery and restoration actions.

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